

Data Sheet No. PD60240 revA

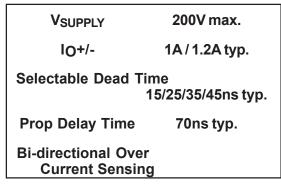
IRS20124S(PbF)

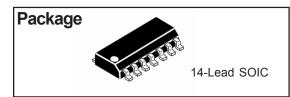
DIGITAL AUDIO DRIVER WITH DISCRETE DEAD-TIME AND PROTECTION

Features

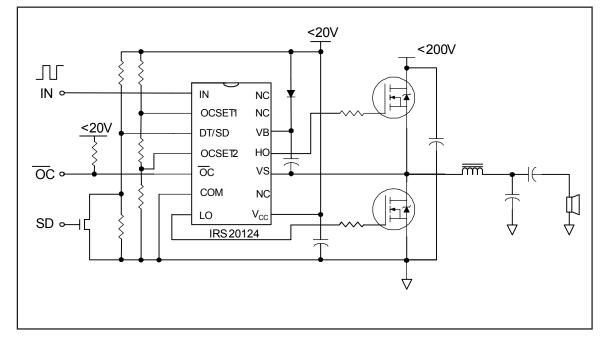
- 200V high voltage ratings deliver up to 1000W output power in Class D audio amplifier applications
- Integrated dead-time generation and bi-directional over current sensing simplify design
- Programmable compensated preset dead-time for improved THD performances over temperature
- High noise immunity
- Shutdown function protects devices from overload conditions
- Operates up to 1MHz
- 3.3V/5V logic compatible input

Product Summary





Typical Application Diagram



Description

The IRS20124S is a high voltage, high speed power MOSFET driver with internal dead-time and shutdown functions specially designed for Class D audio amplifier applications.

The internal dead time generation block provides accurate gate switch timing and enables tight dead-time settings for better THD performances.

In order to maximize other audio performance characteristics, all switching times are designed for immunity from external disturbances such as VCC perturbation and incoming switching noise on the DT pin. Logic inputs are compatible with LSTTL output or standard CMOS down to 3.0V without speed degradation. The output drivers feature high current buffers capable of sourcing 1.0A and sinking 1.2A. Internal delays are optimized to achieve minimal dead-time variations. Proprietary HVIC and latch immune CMOS technologies guarantee operation down to Vs= –4V, providing outstanding capabilities of latch and surge immunities with rugged monolithic construction.

Absolute Maximum Ratings

Absolute maximum ratings indicate sustained limits beyond which damage to the device may occur. All voltage parameters are absolute voltages referenced to COM. All currents are defined positive into any lead. The thermal resistance and power dissipation ratings are measured under board mounted and still air conditions.

| Symbol | Definition | Min. | Max. | Units |
|---------------------|--|--------|---------|-------|
| VB | High side floating supply voltage | -0.3 | 220 | V |
| Vs | High side floating supply voltage | VB-20 | VB+0.3 | V |
| V _{HO} | High side floating output voltage | Vs-0.3 | VB+0.3 | V |
| V _{CC} | Low side fixed supply voltage | -0.3 | 20 | V |
| V _{LO} | Low side output voltage | -0.3 | Vcc+0.3 | V |
| VIN | Input voltage | -0.3 | Vcc+0.3 | V |
| V _{OC} | OC pin input voltage | -0.3 | Vcc+0.3 | V |
| V _{OCSET1} | OCSET1 pin input voltage | -0.3 | Vcc+0.3 | V |
| V _{OCSET2} | OCSET2 pin input voltage | -0.3 | Vcc+0.3 | V |
| dVs/dt | Allowable Vs voltage slew rate | - | 50 | V/ns |
| Pd | Maximum power dissipation | - | 1.25 | W |
| Rth _{JA} | Thermal resistance, Junction to ambient | - | 100 | °C/W |
| TJ | Junction Temperature | - | 150 | °C |
| Ts | Storage Temperature | -55 | 150 | °C |
| TL | Lead temperature (Soldering, 10 seconds) | - | 300 | °C |

Recommended Operating Conditions

For Proper operation, the device should be used within the recommended conditions. The Vs and COM offset ratings are tested with all supplies biased at 15V differential.

| Symbol | Definition | Min. | Max. | Units |
|---------------------|--|--------|----------------|-------|
| VB | High side floating supply absolute voltage | Vs+10 | Vs+18 | V |
| Vs | High side floating supply offset voltage | Note 1 | 200 | V |
| V _{HO} | High side floating output voltage | Vs | V _B | V |
| V _{CC} | Low side fixed supply voltage | 10 | 18 | V |
| V _{LO} | Low side output voltage | 0 | VCC | V |
| VIN | Logic input voltage | 0 | VCC | V |
| V _{OC} | OC pin input voltage | 0 | VCC | V |
| V _{OCSET1} | OCSET1 pin input voltage | 0 | VCC | V |
| V _{OCSET2} | OCSET2 pin input voltage | 0 | VCC | V |
| TA | Ambient Temperature | -40 | 125 | °C |

Note 1: Logic operational for V_S equal to -8V to 200V. Logic state held for V_S equal to -8V to -V_{BS}.

Dynamic Electrical Characteristics

 V_{BIAS} (V_{CC}, V_{BS}) = 15V, C_L = 1nF and T_A = 25°C unless otherwise specified. Figure 2 shows the timing definitions.

| Symbol | Definition | Min. | Тур. | Max. | Units | Test Conditions |
|----------|--|------|------|------|-------|---|
| ton | High & low side turn-on propagation delay | — | 60 | 80 | | V _S =0V |
| toff | High & low side turn-off propagation delay | | 60 | 80 | | V _S =200V |
| tr | Turn-on rise time | — | 25 | 40 | | |
| tf | Turn-off fall time | — | 15 | 35 | | |
| tsd | Shutdown propagation delay | — | 140 | 200 | | |
| toc | Propagation delay time from Vs>Vsoc+ to OC | — | 280 | _ | | OC _{SET1} =3.22V |
| | | | | | | OC _{SET2} =1.20V |
| twoc min | OC pulse width | | 100 | | nsec | |
| toc filt | OC input filter time | | 200 | _ | | |
| DT1 | Deadtime: LO turn-off to HO turn-on (DT _{LO-HO}) | | | | | |
| | & HO turn-off to LO turn-on (DT _{HO-LO}) | 0 | 15 | 40 | | V _{DT} >V _{DT1} |
| DT2 | Deadtime: LO turn-off to HO turn-on (DT _{LO-HO}) | | | | | |
| | & HO turn-off to LO turn-on (DT _{HO-LO}) | | 25 | 50 | | V _{DT1} >V _{DT} >V _{DT2} |
| DT3 | Deadtime: LO turn-off to HO turn-on (DT _{LO-HO}) | | | | | |
| | & HO turn-off to LO turn-on (DT _{HO-LO}) | | 35 | 60 | | V _{DT2} >V _{DT} >V _{DT3} |
| DT4 | Deadtime: LO turn-off to HO turn-on (DT_{LO-HO}) | | | | | |
| | & HO turn-off to LO turn-on (DT _{HO-LO})V _D T= V _{DT4} | 15 | 45 | 70 | | V_{DT3} > V_{DT} > V_{DT4} |

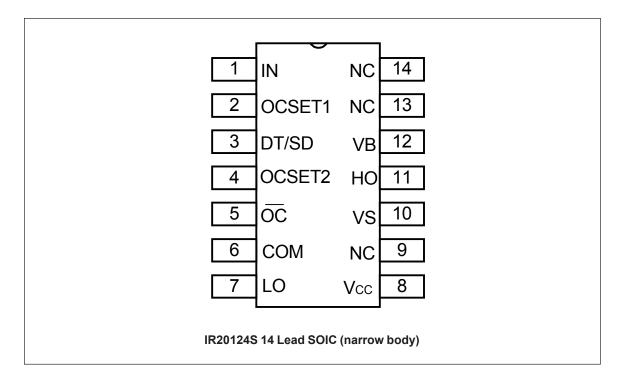
Static Electrical Characteristics

 $V_{BIAS}~(V_{CC},~V_{BS})$ = 15V and T_A = 25°C unless otherwise specified.

| Symbol | Definition | Min. | Тур. | Max. | Units | Test Conditions |
|-------------------|---|----------|----------|----------|-------|----------------------------------|
| VIH | Logic high input voltage | 2.5 | | | | Vcc=10~20V |
| VIL | Logic low input voltage | | _ | 1.2 | Ī | |
| V _{OH} | High level output voltage, $V_{BIAS} - V_O$ | _ | _ | 1.2 | Ī | lo=0A |
| V _{OL} | Low level output voltage, V _O | — | — | 0.1 | V | lo=0A |
| UV _{CC+} | Vcc supply UVLO positive threshold | 8.3 | 9.0 | 9.7 | v | |
| UV _{CC-} | Vcc supply UVLO negative threshold | 7.5 | 8.2 | 8.9 | | |
| UV _{BS+} | High side well UVLO positive threshold | 8.3 | 9.0 | 9.7 | Ī | |
| UV _{BS-} | High side well UVLO negative threshold | 7.5 | 8.2 | 8.9 | Ī | |
| I _{QBS} | High side quiescent current | — | — | 1 | | |
| I _{QCC} | Low side quiescent current | — | — | 4 | mA | V _{DT} =V _{CC} |
| I _{LK} | High to Low side leakage current | — | — | 50 | | $V_B = V_S = 200V$ |
| I _{IN+} | Logic "1" input bias current | — | 3 | 10 | μA | V _{IN} =3.3V |
| I _{IN-} | Logic "0" input bias current | — | 0 | 1.0 | | V _{IN} =0V |
| I ₀₊ | Output high short circuit current (Source) | — | 1.0 | — | A | Vo=0V, PW<10µS |
| I _{o-} | Output low short circuit current (Sink) | — | 1.2 | — | | Vo=15V, PW<10µS |
| V _{DT1} | DT mode select threshold 1 | 0.8xVcc | 0.89xVcc | 0.97xVcc | | |
| V _{DT2} | DT mode select threshold 2 | 0.51xVcc | 0.57xVcc | 0.63xVcc | | |
| V _{DT3} | DT mode select threshold 3 | 0.32xVcc | 0.36xVcc | 0.40xVcc | | |
| V _{DT4} | DT mode select threshold 4 | 0.21xVcc | 0.23xVcc | 0.25xVcc | V | |
| V _{SOC+} | Positive OC threshold in Vs | 0.75 | 1.0 | 1.25 | V | OC _{SET1} =3.22V |
| | | | | | | OC _{SET} 2=1.20 |
| V _{SOC-} | Negative OC threshold in Vs | -1.25 | -1.0 | -0.75 | Ī | OC _{SET1} =3.22V |
| | | | | | | OC _{SET2} =1.20V |

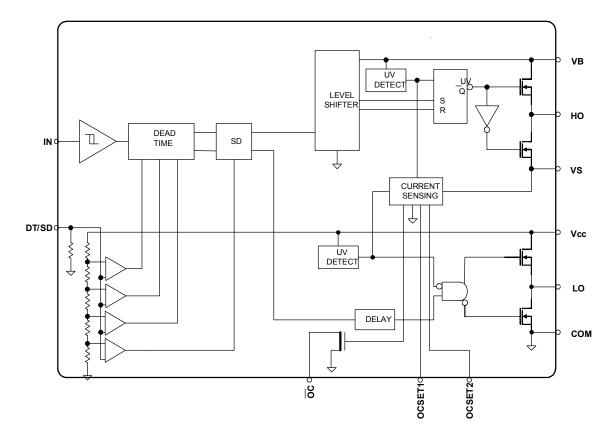
Lead Definitions

| Symbol | Description |
|--------------------|--|
| VCC | Low side logic Supply voltage |
| VB | High side floating supply |
| HO | High side output |
| VS | High side floating supply return |
| IN | Logic input for high and low side gate driver outputs (HO and LO), in phase with HO |
| DT/SD | Input for programmable dead-time, referenced to COM. Shutdown LO and HO when tied to COM |
| COM | Low side supply return |
| LO | Low side output |
| OC | Over current output (negative logic) |
| OC _{SET1} | Input for setting negative over current threshold |
| OC _{SET2} | Input for setting positive over current threshold |



International **IOR** Rectifier

Block Diagram



International **tor** Rectifier

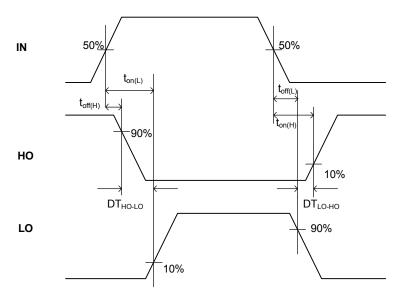


Figure 1. Switching Time Waveform Definitions

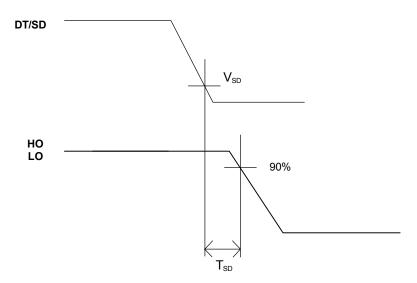


Figure 2. Shutdown Waveform Definitions

International **tor** Rectifier

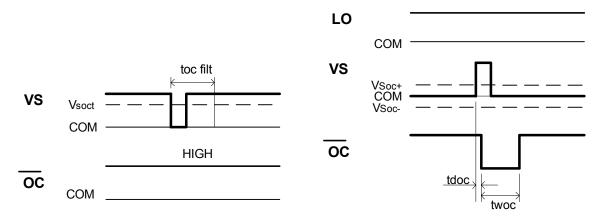


Figure 3. OC Input FilterTime Definitions

Figure 4. OC Waveform Definitions

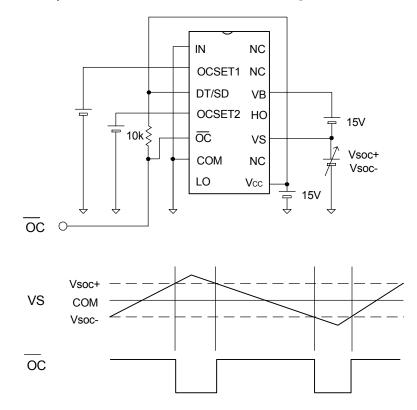
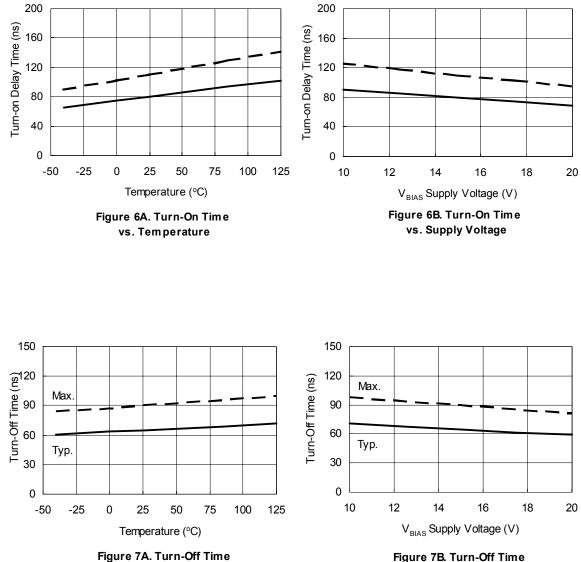


Figure 5. OC Waveform Definitions

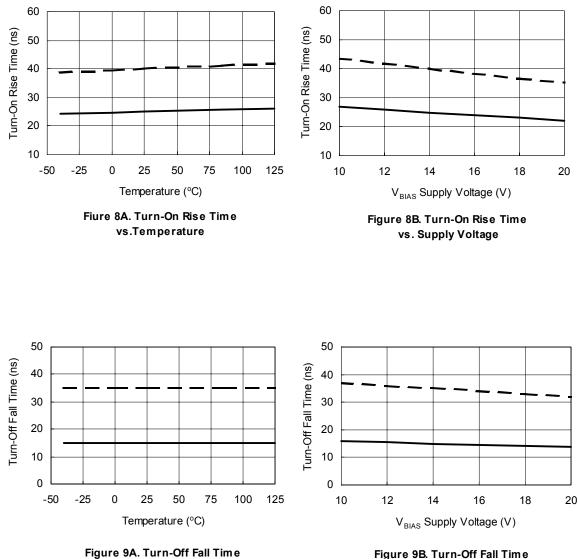
International **tor** Rectifier

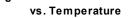


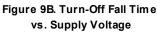
vs. Temperature

Figure 7B. Turn-Off Time vs. Supply Voltage

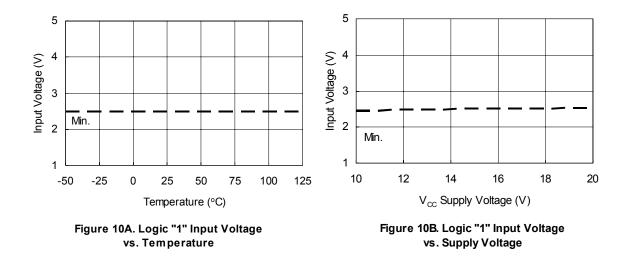
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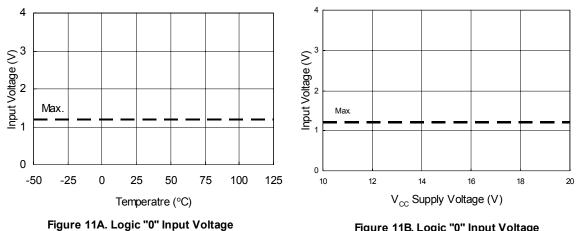




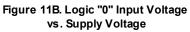




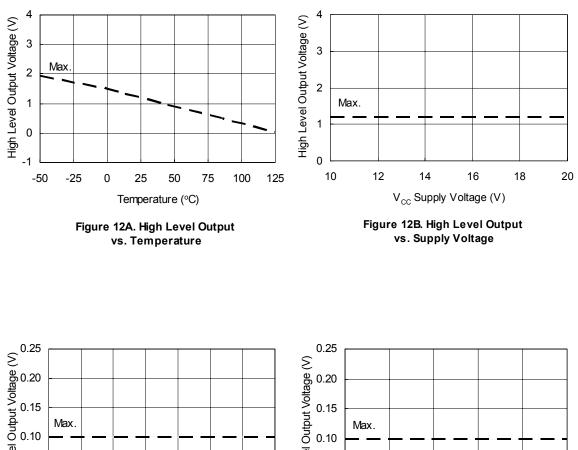


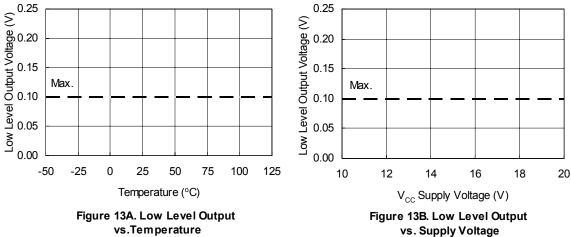


vs. Temperature



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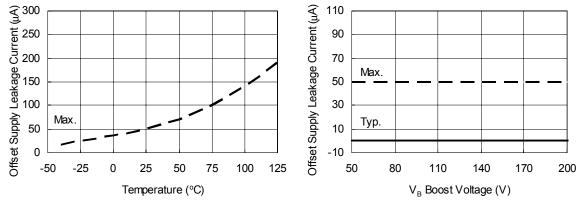
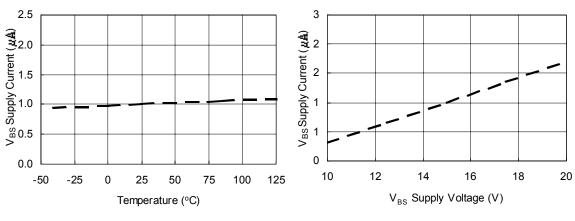
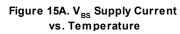
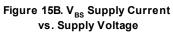


Figure 14A. Offset Supply Leakage Current vs. Temperature V_B=200v

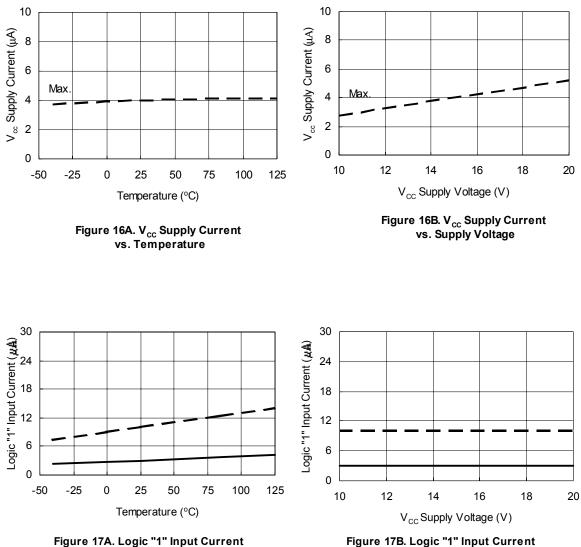
Figure 14B. Offset Supply Leakage Current vs. Supply Voltage







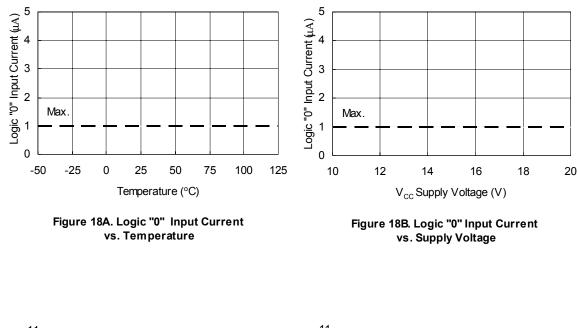
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vs. Temperature

igure 17B. Logic "1" Input Current vs. Supply Voltage





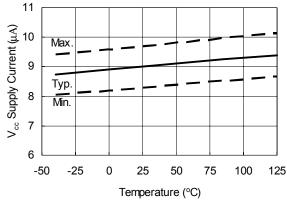
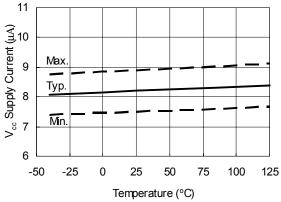
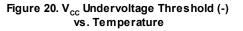


Figure 19. V_{cc} Undervoltage Threshold (+) vs. Temperature





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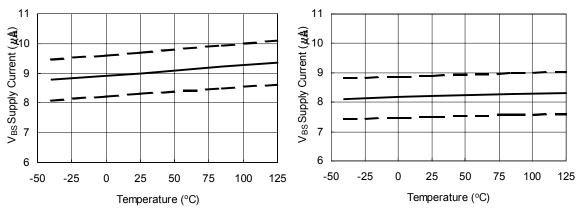
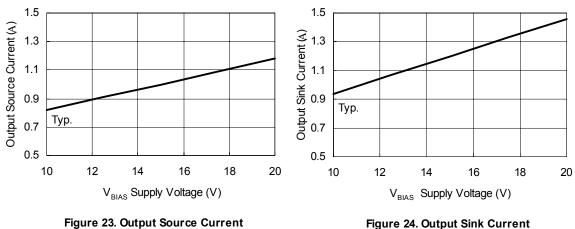


Figure 21. V_{BS} Undervoltage Threshold (+) vs. Temperature

Figure 22. V_{BS} Undervoltage Threshold (-) vs. Temperature



vs. Supply Voltage

Figure 24. Output Sink Current vs. Supply Voltage



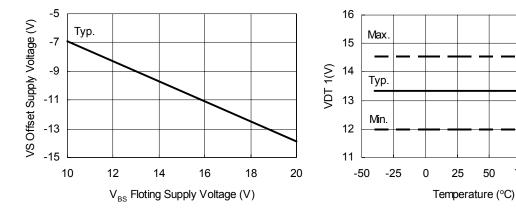
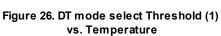


Figure 25. Maximum VS Negative Offset vs. Supply Voltage



75

100

125

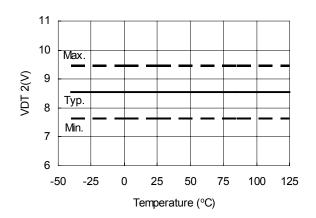


Figure 27. DT mode select Threshold (2) vs. Temperature

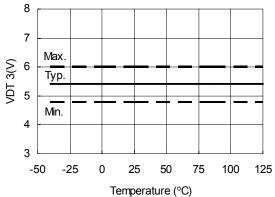


Figure 28. DT mode select Threshold (3) vs. Temperature

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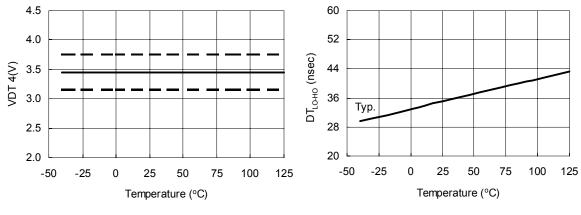
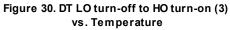


Figure 29. DT mode select Threshold (4) vs. Temperature



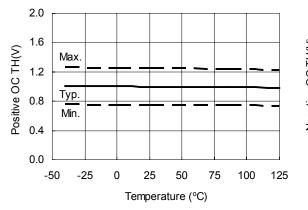
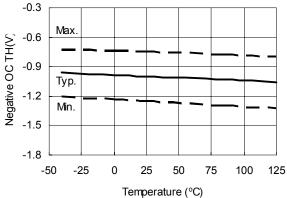
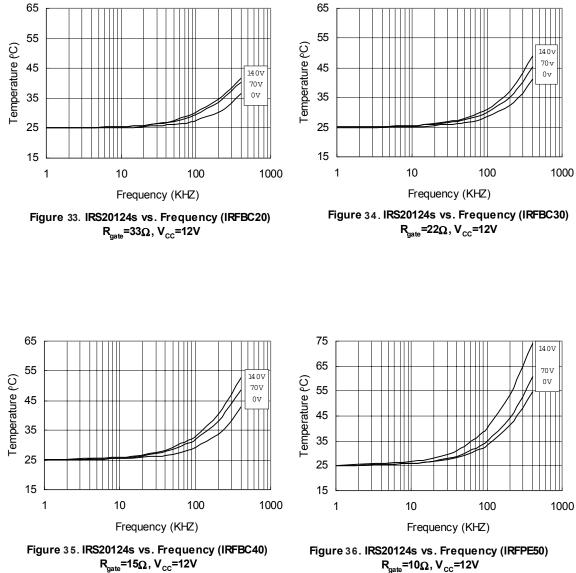


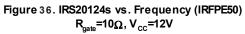
Figure 31. Positive OC Threshold(+) in VS vs. Temperature











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Functional description

Programmable Dead-time

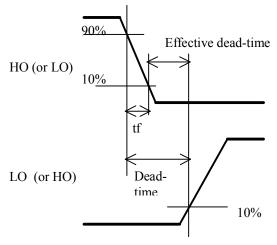
The IRS20124 has an internal dead-time generation block to reduce the number of external components in the output stage of a Class D audio amplifier. Selectable dead-time through the DT/SD pin voltage is an easy and reliable function, which requires only two external resistors. The dead-time generation block is also designed to provide a constant dead-time interval, independent of Vcc fluctuations. Since the timings are critical to the audio performance of a Class D audio amplifier, the unique internal dead-time generation block is designed to be immune to noise on the DT/SD pin and the Vcc pin. Noise-free programmable dead-time function is available by selecting deadtime from four preset values, which are optimized and compensated.

How to Determine Optimal Dead-time

Please note that the effective dead-time in an actual application differs from the dead-time specified in this datasheet due to finite fall time, tf. The dead-time value in this datasheet is defined as the time period from the starting point of turn-off on one side of the switching stage to the starting point of turn-on on the other side as shown in Fig.5. The fall time of MOSFET gate voltage must be sub-tracted from the dead-time value in the datasheet to determine the effective dead time of a Class D audio amplifier.

(Effective dead-time)

= (Dead-time in datasheet) - (fall time, tf)





A longer dead time period is required for a MOSFET with a larger gate charge value because of the longer tf. A shorter effective dead-time setting is always beneficial to achieve better linearity in the Class D switching stage. However, the likelihood of shoot-through current increases with narrower dead-time settings in mass production. Negative values of effective dead-time may cause excessive heat dissipation in the MOSFETs, potentially leading to their serious damage. To calculate the optimal dead-time in a given application, the fall time tf for both output voltages, HO and LO, in the actual circuit needs to be measured. In addition, the effective dead-time can also vary with temperature and device parameter variations. Therefore, a minimum effective dead-time of 10nS is recommended to avoid shoot-through current over the range of operating temperatures and supply voltages.

DT/SD pin

DT/SD pin provides two functions: 1) setting deadtime and 2) shutdown. The IRS20124 determines its operation mode based on the voltage applied to the DT/SD pin. An internal comparator translates which mode is being used by comparing internal reference voltages. Threshold voltages for each mode are set internally by a resistive voltage divider off Vcc, negating the need of using a precise absolute voltage to set the mode.

The relationship between the operation mode and the voltage at DT/SD pin is illustrated in the Fig.7.

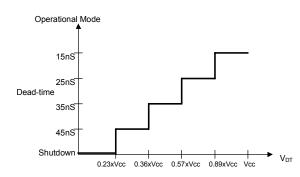


Figure 7. Dead-time Settings vs V_{DT} Voltage

Design Example

Table 1 shows suggested values of resistance for setting the dead-

time. Resistors with up to 5% tolerance can be used if these listed values are followed.

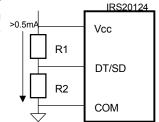


Figure 8. External Resistor

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| Dead- time mode | R1 | R2 | DT/SD voltage |
|-----------------------|------|------|------------------|
| DT1 | <10k | Open | 1.0 x Vcc |
| DT2 | 3.3k | 8.2k | 0.71 x Vcc |
| DT3 | 5.6k | 4.7k | 0.46 x Vcc |
| DT4 | 8.2k | 3.3k | 0.29 x Vcc |

| Table | 1. | Suggested | resistor | values | for | dead-time |
|----------|----|-----------|----------|--------|-----|-----------|
| settings | | | | | | |

Shutdown

Since IRS20124 has internal dead-time generation, independent inputs for HO and LO are no longer provided. Shutdown mode is the only way to turn off both MOSFETs simultaneously to protect them from over current conditions. If the DT/SD pin detects an input voltage below the threshold, V_{DT4} , the IRS20124 will output 0V at both HO and LO outputs, forcing the switching output node to go into a high impedance state.

Over Current Sensing

In order to protect the power MOSFET, IRS20124 has a feature to detect over current conditions, which can occur when speaker wires are shorted together. The over current shutdown feature can be configured by combining the current sensing function with the shutdown mode via the DT/SD pin.

Load Current Direction in Class D Audio Application

In a Class D audio amplifier, the direction of the load current alternates according to the audio input signal. An over current condition can therefore happen during either a positive current cycle or a negative current cycle. Fig.9 shows the rela-

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tionship between output current direction and the current in the low side MOSFET. It should be noted that each MOSFET carries a part of the load current in an audio cycle. Bi-directional current sensing offers over current detection capabilities in both cases by monitoring only the low side MOSFET.

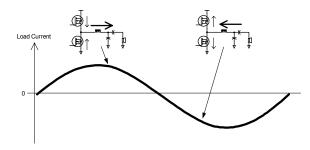


Figure 9. Direction in MMOSFET Current and Load Current

Bi-directional Current Sensing

IRS20124 has an over current detection function utilizing $R_{DS(ON)}$ of the low side switch as a current sensing shunt resistor. Due to the proprietary HVIC process, the IRS20124 is able to sense negative as well as positive current flow, enabling bi-directional load current sensing without the need for any additional external passive components.

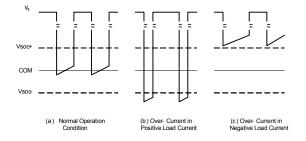


Figure 10. Vs Waveform in Over-current Condition

IRS20124 measures the current during the period when the low side MOSFET is turned on. Fig.10 illustrates how an excessive voltage at Vs node detects an over current condition. Under normal operating conditions, Vs voltage for the low side switch is well within the trip threshold boundaries, V_{soc-} and V_{soc+} . In the case of Fig.9(b) which demonstrates the amplifier sourcing too much current to the load, the Vs node is found below the trip level, V_{soc-} . In Fig.9(c) with opposite current direction, the amplifier sinks too much current from the load, positioning Vs well above trip level, V_{soc+}

Once the voltage in Vs exceeds the preset threshold, the OC pin pulls down to COM to detect an over current condition.

Since the switching waveform usually contains over/under shoot and associated oscillatory artifacts on their transient edges, a 200ns blanking interval is inserted in the Vs voltage sensing block at the instant the low side switch is engaged. Because of this blanking interval, the OC function will be unable to detect over current conditions if the low side ON duration less than 200ns.

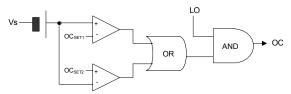


Figure 11. Simplified Functional Block Diagram of Bi-Directional Current Sensing

As shown in Fig.11, bi-directional current sensing block has an internal 2.0V level shifter feeding the signal to the comparator. OC_{SET1} sets the positive side threshold, and is given a trip level at V_{SOC+} , which is OC_{SET1} - 2.0V. In same way, for a given OC_{SET2} , V_{SOC-} is set at OC_{SET2} - 2.0V

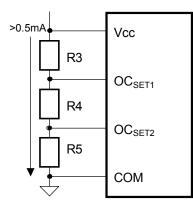


Figure 12. External Resistor Network to set OC Threshold

How to set OC Threshold

The positive and negative trip thresholds for bidirectional current sensing are set by the voltages at OC_{SET1} and OC_{SET2} . Fig.14 shows a typical resistor voltage divider that can. be used to set OC_{SET1} and OC_{SET2} .

The trip threshold voltages, V_{SOC+} and V_{SOC+} are determined by the required trip current levels, I_{TRIP+} and I_{TRIP-}, and R_{DS(ON)} in the low side MOSFET. Since the sensed voltage of Vs is shifted up by 2.21V internally and compared with the voltages fed to the OC_{SET1} and OC_{SET2} pins, the required value of OC_{SET1} with respect to COM is

 $V_{OCSET1} = V_{SOC+} + 2.21 = I_{TRIP+} \times R_{DS(ON)} + 2.21$

The same relation holds between OC_{SET2} and V_{SOC}

$$V_{OCSET2} = V_{SOC-} + 2.21 = I_{TRIP-} \times R_{DS(ON)} + 2.21$$

In general, $R_{DS(ON)}$ has a positive temperature coefficient that needs to be considered when the

threshold level is being set. Please also note that, in the negative load current direction, the sensing voltage at the Vs node is limited by the body diode of the low side MOSFET as explained later.

Design Example

This example demonstrates how to use the external? resistor network to set I_{TRIP+} and I_{TRIP-} to be ±11A, using a MOSFET that has $R_{DS(ON)}$ =60m Ω .

$$\begin{split} & \mathsf{V}_{\mathsf{ISET1}} = \mathsf{V}_{\mathsf{TH}} + \ + \ 2.21 = \mathsf{I}_{\mathsf{TRIP}} \ x \ \mathsf{R}_{\mathsf{DS(ON)}} \ + \ 2.21 = \ 11 \\ & x \ 60 \text{m}\Omega \ + 2.21 = \ 2.87 \text{V} \\ & \mathsf{V}_{\mathsf{ISET2}} = \mathsf{V}_{\mathsf{TH}} \ + \ 2.21 = \ \mathsf{I}_{\mathsf{TRIP}} \ x \ \mathsf{R}_{\mathsf{DS(ON)}} \ + \ 2.21 = \ (-11) \\ & x \ 60 \text{m}\Omega \ + 2.21 = \ 1.55 \text{V} \end{split}$$

The total resistance of resistor network is based on the voltage at the Vcc and required bias current in this resistor network.

$$R_{total} = R3 + R4 + R5 = Vcc / I_{bias}$$
$$= 12V / 1mA = 12K\Omega$$

The expected voltage across R3 is Vcc- V_{ISET1} = 12-2.87=9.13V. Similarly, the voltages across R4 is $V_{SOC+} - V_{SOC-}$ = 2.87-1.55=1.32V, and the voltage across R5 is V_{ISET2} = 1.55V respectively.

 $\begin{array}{l} {\sf R3=}9.13{\sf V}/\;{\sf I}_{\rm bias}=9.13{\sf K}\Omega\\ {\sf R4=}1.32{\sf V}/\;{\sf I}_{\rm bias}=1.32{\sf K}\Omega\\ {\sf R5=}1.55{\sf V}/\;{\sf I}_{\rm bias}=1.55{\sf K}\Omega \end{array}$

Choose R3= $9.09K\Omega$, R4= $1.33K\Omega$, R5= $1.54K\Omega$ from E-96 series.

Consequently, actual threshold levels are V_{SOC+} =2.88V gives I_{TRIP+} = 11.2A V_{SOC-} =1.55V gives I_{TRIP-} = -11.0A

Resisters with 1% tolerances are recommended.

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OC Output Signal

The OC pin is a 20V open drain output. The OC pin is pulled down to ground when an over current condition is detected. A single external pull-up resistor can be shared by multiple IRS20124 OC pins to form the ORing logic. In order for a micro-processor to read the OC signal, this information is buffered with a mono stable multi vibrator to ensure 100ns minimum pulse width.

Because of unpredictable logic status of the OC pin, the OC signal should be ignored during power up/down.

Limitation from Body Diode in MOSFET

When a Class D stage outputs a positive current, flowing from the Class D amp to the load, the body diode of the MOSFET will turn on when the Drain to Source voltage of the MOSFET become larger than the diode forward drop voltage. In such a case, the sensing voltage at the Vs pin of the IRS20124 is clamped by the body diode. This means that the effective Rds(on) is now much lower than expected from Rds(on) of the MOSFET, and the Vs node my not able to reach the threshold to turn the OC output on before the MOSFET fails. Therefore, the region where body diode clamping takes a place should be avoided when setting V_{socc} .

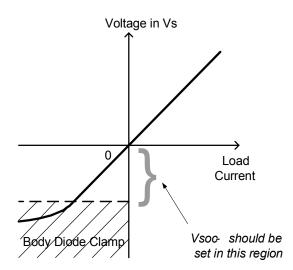


Figure 13. Body Diode in MOSFET Clamps vs Voltage

For further application information for gate driver IC please refer to AN-978 and DT98-2a. For further application information for class D application, please refer to AN-1070 and AN-1071.

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